

PT20SD Position Transmitter

Calibration Instructions

For use with SMB, L120 and LY actuators, with or without integral control packages.





Calibration procedure

- 1. Position the actuator to mid-travel (valve at 50% position).
- 2. Disconnect the potentiometer wiring harness from the PT20SD board and measure the resistance from each end connection to the center connection on the potentiometer.
- To set the potentiometer to the correct resistance reading, loosen the setscrew that retains the spur gear on the potentiometer shaft and rotate the shaft until a reading of 500 (ohms) is achieved.
- 4. Tighten the setscrew and reconnect the wiring harness to the PT20SD.
- 5. Run the actuator fully CLOSED.
- Calibrate ZERO position by adjusting the zero potentiometer until a 4 mA output signal is read at terminals +VE and -VE.
- 7. Run the actuator fully OPEN.
- Calibrate SPAN position by adjusting the span potentiometer until a 20 mA output signal is read at terminals +VE and -VE.
- 9. Repeat steps 5 to 8 and fine-tune as necessary.

Important notes

- 1. Analog inputs must not be connected to earth ground on +VE or -VE terminal.
- 2. For actuators equipped with 18 VAC input, move jumpers LK2 and LK3 to the AC position.

Specifications

- Output signal: 4-20 mA
- Input potentiometer: 1K (ohms)
- Temperature rating: -40 to +85°C
- Linearity error: ±1% max.
- Loop resistance: 370 (ohms) max.
- **Power:** 18 VAC or 24 VDC ± 10% (LK2 and LK3 must be set appropriately.)



Experience In Motion







The PT20SD signal converter may be powered by either 24 VDC or 18 VAC. The board is wired to a 1K ohm potentiometer mounted to the position indicator gearing in the actuator. The board circuitry converts the 1K ohm input to a 4-20 mA output for valve position indication.

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